Dixièmes Journées Franco-Chiliennes d'Optimisation INSA Rouen Normandie, Rouen, France 8-11 July 2025

DIFFERENTIABILITY OF PROBABILITY FUNCTIONS INVOLVING STAR-SHAPED VALUED SET-VALUED MAPS.

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Motivated by a control-theoretic example in which system dynamics are influenced by uncertainty and a predetermined "here-and-now" control input, we define a feasible trajectory as one that reaches the target with high probability. This leads to a probability function that quantifies the likelihood associated with a random vector belonging to a star-shaped set. Consequently, we are motivated to explore the properties of probability functions acting on parameter-dependent star-shaped sets.

In this talk, we illustrate through examples that, although star-shapedness closely resembles convexity, it is not sufficient to guarantee locally Lipschitz continuity of the associated probability functions. To address this limitation, we propose an intuitive regularization of the star-shapedness concept. Under this regularization, and with additional reasonable assumptions, we derive "computable" expressions for the generalized subdifferentials of the resulting probability functions.

References

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